

# Telemecanique Uni-Telway Driver

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## Welcome to the Telemecanique Uni-Telway Driver Help Center

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This help center is the user documentation for Kepware Telemecanique Uni-Telway Driver. This help center is updated regularly to reflect the latest functionality and information.

### [Overview](#)

What is the Telemecanique Uni-Telway Driver?

### [Setup](#)

How do I configure a device for use with this driver?

### [Data Types Description](#)

What data types does this driver support?

### [Address Descriptions](#)

How do I address a data location on a Telemecanique device?

### [Error Descriptions](#)

What messages does the Telemecanique Uni-Telway Driver produce?

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## Overview

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The Telemecanique Uni-Telway Driver provides a reliable way to connect Telemecanique Uni-Telway devices to OPC client applications; including HMI, SCADA, Historian, MES, ERP, and countless custom applications. It is intended for use with Telemecanique devices that communicate using the Uni-Telway protocol.

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## Setup

### Supported Devices

Large Frame and Small Frame. Telemecanique Devices that do not support the full 128-byte data field provided by the Telemecanique Uni-Telway protocol are considered Small Frame. One example of a Small Frame device is the TSX17-20.

### Communication Protocol

Uni-Telway

### Supported Communication Properties

Baud Rate: 1200, 2400, 9600, 19200 or 38400

Parity: None, Even or Odd

Data Bits: 5, 6, 7 or 8

Stop Bits: 1 or 2

● **Note:** Due to the nature of the Uni-Telway protocol, users may be required to disable FIFO buffer usage on the COM port(s) that have been selected for use with this driver.

### Converters

Depending on type of PLC being used, the TSX SCA 72 converter may not work. The TSX SCA 72 requires that the PC control the switching of the RS-485 transmitter / receiver on and off. This is done using the RTS line from the serial port. PLCs like the TSX37 respond quickly to the Telemecanique Uni-Telway Driver: the Windows communication driver is not fast enough to effectively control the TSX SCA 72s RS-485 line converter.

Schneider Automation (Electric) makes a modem cable that should work. The cable was designed for devices that do not manage the RTS signal. The part # is: TSX PCX 1031.

● **Note:** Converters are to be used with our 32-bit Telemecanique Uni-Telway Driver.

### Channel and Device Limits

The maximum number of channels supported by this driver is 100.

### Ethernet Encapsulation

This driver does not support Ethernet Encapsulation.

### Flow Control

When using an RS232 / RS485 converter, the type of flow control that is required will depend upon the needs of the converter. Some converters do not require any flow control and others will require RTS flow. To determine the converter's flow requirements, refer to its documentation. We recommend using an RS485 converted that provides automatic flow control.

● **Note:** When using the manufacturer's supplied communications cable, it is sometimes necessary to choose a flow control property of **RTS** or **RTS Always** under the Channel Properties.

## Channel Properties – General

This server supports the use of multiple simultaneous communications drivers. Each protocol or driver used in a server project is called a channel. A server project may consist of many channels with the same communications driver or with unique communications drivers. A channel acts as the basic building block of an OPC link. This group is used to specify general channel properties, such as the identification attributes and operating mode.

Property Groups	[-] <b>Identification</b>	
<b>General</b>	Name	
Write Optimizations	Description	
Advanced	Driver	
	[-] <b>Diagnostics</b>	
	Diagnostics Capture	Disable
	[-] <b>Tag Counts</b>	
	Static Tags	10

### Identification

**Name:** Specify the user-defined identity of this channel. In each server project, each channel name must be unique. Although names can be up to 256 characters, some client applications have a limited display window when browsing the OPC server's tag space. The channel name is part of the OPC browser information. The property is required for creating a channel.

• For information on reserved characters, refer to "How To... Properly Name a Channel, Device, Tag, and Tag Group" in the server help.

**Description:** Specify user-defined information about this channel.

• Many of these properties, including Description, have an associated system tag.

**Driver:** Specify the protocol / driver for this channel. Specify the device driver that was selected during channel creation. It is a disabled setting in the channel properties. The property is required for creating a channel.

• **Note:** With the server's online full-time operation, these properties can be changed at any time. This includes changing the channel name to prevent clients from registering data with the server. If a client has already acquired an item from the server before the channel name is changed, the items are unaffected. If, after the channel name has been changed, the client application releases the item and attempts to re-acquire using the old channel name, the item is not accepted. Changes to the properties should not be made once a large client application has been developed. Utilize proper user role and privilege management to prevent operators from changing properties or accessing server features.

### Diagnostics

**Diagnostics Capture:** When enabled, this option makes the channel's diagnostic information available to OPC applications. Because the server's diagnostic features require a minimal amount of overhead processing, it is recommended that they be utilized when needed and disabled when not. The default is disabled.

• **Note:** This property is not available if the driver or operating system does not support diagnostics.

• For more information, refer to *Communication Diagnostics and Statistics Tags* in server help.

### Tag Counts

**Static Tags:** Provides the total number of defined static tags at this level (device or channel). This information can be helpful in troubleshooting and load balancing.

## Channel Properties – Serial Communications

Serial communication properties are available to serial drivers and vary depending on the driver, connection type, and options selected. Below is a superset of the possible properties.

Click to jump to one of the sections: [Connection Type](#), [Serial Port Settings](#), and [Operational Behavior](#).

• **Notes:**

- With the server's online full-time operation, these properties can be changed at any time. Utilize proper user role and privilege management to prevent operators from changing properties or accessing server features.
- Users must define the specific communication parameters to be used. Depending on the driver, channels may or may not be able to share identical communication parameters. Only one shared serial connection can be configured for a Virtual Network (see [Channel Properties – Serial Communications](#)).

Property Groups	<input type="checkbox"/> <b>Connection Type</b>	
General	Physical Medium	COM Port
<b>Serial Communications</b>	<input type="checkbox"/> <b>Serial Port Settings</b>	
Write Optimizations	COM ID	39
Advanced	Baud Rate	19200
	Data Bits	8
	Parity	None
	Stop Bits	1
	Flow Control	RTS Always
	<input type="checkbox"/> <b>Operational Behavior</b>	
	Report Communication Errors	Enable
	Close Idle Connection	Enable
	Idle Time to Close (s)	15

## Connection Type

**Physical Medium:** Choose the type of hardware device for data communications. Options include Modem, COM Port, and None. The default is COM Port.

1. **None:** Select None to indicate there is no physical connection, which displays the [Operation with no Communications](#) section.
2. **COM Port:** Select Com Port to display and configure the [Serial Port Settings](#) section.
3. **Modem:** Select Modem if phone lines are used for communications, which are configured in the [Modem Settings](#) section.
4. **Shared:** Verify the connection is correctly identified as sharing the current configuration with another channel. This is a read-only property.

## Serial Port Settings

**COM ID:** Specify the Communications ID to be used when communicating with devices assigned to the channel. The valid range is 1 to 9991 to 16. The default is 1.

**Baud Rate:** Specify the baud rate to be used to configure the selected communications port.

**Data Bits:** Specify the number of data bits per data word. Options include 5, 6, 7, or 8.


**Parity:** Specify the type of parity for the data. Options include Odd, Even, or None.

**Stop Bits:** Specify the number of stop bits per data word. Options include 1 or 2.

**Flow Control:** Select how the RTS and DTR control lines are utilized. Flow control is required to communicate with some serial devices. Options are:

- **None:** This option does not toggle or assert control lines.
- **DTR:** This option asserts the DTR line when the communications port is opened and remains on.
- **RTS:** This option specifies that the RTS line is high if bytes are available for transmission. After all buffered bytes have been sent, the RTS line is low. This is normally used with RS232/RS485 converter hardware.
- **RTS, DTR:** This option is a combination of DTR and RTS.

- **RTS Always:** This option asserts the RTS line when the communication port is opened and remains on.
- **RTS Manual:** This option asserts the RTS line based on the timing properties entered for RTS Line Control. It is only available when the driver supports manual RTS line control (or when the properties are shared and at least one of the channels belongs to a driver that provides this support). RTS Manual adds an **RTS Line Control** property with options as follows:
  - **Raise:** Specify the amount of time that the RTS line is raised prior to data transmission. The valid range is 0 to 9999 milliseconds. The default is 10 milliseconds.
  - **Drop:** Specify the amount of time that the RTS line remains high after data transmission. The valid range is 0 to 9999 milliseconds. The default is 10 milliseconds.
  - **Poll Delay:** Specify the amount of time that polling for communications is delayed. The valid range is 0 to 9999. The default is 10 milliseconds.

 **Tip:** When using two-wire RS-485, "echoes" may occur on the communication lines. Since this communication does not support echo suppression, it is recommended that echoes be disabled or a RS-485 converter be used.

## Operational Behavior

- **Report Communication Errors:** Enable or disable reporting of low-level communications errors. When enabled, low-level errors are posted to the Event Log as they occur. When disabled, these same errors are not posted even though normal request failures are. The default is Enable.
- **Close Idle Connection:** Choose to close the connection when there are no longer any tags being referenced by a client on the channel. The default is Enable.
- **Idle Time to Close:** Specify the amount of time that the server waits once all tags have been removed before closing the COM port. The default is 15 seconds.

## Modem Settings

- **Modem:** Specify the installed modem to be used for communications.
- **Connect Timeout:** Specify the amount of time to wait for connections to be established before failing a read or write. The default is 60 seconds.
- **Modem Properties:** Configure the modem hardware. When clicked, it opens vendor-specific modem properties.
- **Auto-Dial:** Enables the automatic dialing of entries in the Phonebook. The default is Disable. *For more information, refer to "Modem Auto-Dial" in the server help.*
- **Report Communication Errors:** Enable or disable reporting of low-level communications errors. When enabled, low-level errors are posted to the Event Log as they occur. When disabled, these same errors are not posted even though normal request failures are. The default is Enable.
- **Close Idle Connection:** Choose to close the modem connection when there are no longer any tags being referenced by a client on the channel. The default is Enable.
- **Idle Time to Close:** Specify the amount of time that the server waits once all tags have been removed before closing the modem connection. The default is 15 seconds.

## Operation with no Communications

- **Read Processing:** Select the action to be taken when an explicit device read is requested. Options include Ignore and Fail. Ignore does nothing; Fail provides the client with an update that indicates failure. The default setting is Ignore.

## Channel Properties – Write Optimizations

The server must ensure that the data written from the client application gets to the device on time. Given this goal, the server provides optimization properties to meet specific needs or improve application responsiveness.

Property Groups	[-] <b>Write Optimizations</b>	
General	Optimization Method	Write Only Latest Value for All Tags
<b>Write Optimizations</b>	Duty Cycle	10

### Write Optimizations

**Optimization Method:** Controls how write data is passed to the underlying communications driver. The options are:

- **Write All Values for All Tags:** This option forces the server to attempt to write every value to the controller. In this mode, the server continues to gather write requests and add them to the server's internal write queue. The server processes the write queue and attempts to empty it by writing data to the device as quickly as possible. This mode ensures that everything written from the client applications is sent to the target device. This mode should be selected if the write operation order or the write item's content must uniquely be seen at the target device.
- **Write Only Latest Value for Non-Boolean Tags:** Many consecutive writes to the same value can accumulate in the write queue due to the time required to actually send the data to the device. If the server updates a write value that has already been placed in the write queue, far fewer writes are needed to reach the same final output value. In this way, no extra writes accumulate in the server's queue. When the user stops moving the slide switch, the value in the device is at the correct value at virtually the same time. As the mode states, any value that is not a Boolean value is updated in the server's internal write queue and sent to the device at the next possible opportunity. This can greatly improve the application performance.
  - **Note:** This option does not attempt to optimize writes to Boolean values. It allows users to optimize the operation of HMI data without causing problems with Boolean operations, such as a momentary push button.
- **Write Only Latest Value for All Tags:** This option takes the theory behind the second optimization mode and applies it to all tags. It is especially useful if the application only needs to send the latest value to the device. This mode optimizes all writes by updating the tags currently in the write queue before they are sent. This is the default mode.

**Duty Cycle:** is used to control the ratio of write to read operations. The ratio is always based on one read for every one to ten writes. The duty cycle is set to ten by default, meaning that ten writes occur for each read operation. Although the application is performing a large number of continuous writes, it must be ensured that read data is still given time to process. A setting of one results in one read operation for every write operation. If there are no write operations to perform, reads are processed continuously. This allows optimization for applications with continuous writes versus a more balanced back and forth data flow.

● **Note:** It is recommended that the application be characterized for compatibility with the write optimization enhancements before being used in a production environment.

## Channel Properties – Advanced

This group is used to specify advanced channel properties. Not all drivers support all properties; so the Advanced group does not appear for those devices.

Property Groups	[-] <b>Non-Normalized Float Handling</b>	
General	Floating-Point Values	Replace with Zero
Write Optimizations	[-] <b>Inter-Device Delay</b>	
<b>Advanced</b>	Inter-Device Delay (ms)	0

**Non-Normalized Float Handling:** A non-normalized value is defined as Infinity, Not-a-Number (NaN), or as a Denormalized Number. The default is Replace with Zero. Drivers that have native float handling may default to Unmodified. Non-normalized float handling allows users to specify how a driver handles IEEE-754 floating point data. Descriptions of the options are as follows:

- **Replace with Zero:** This option allows a driver to replace non-normalized IEEE-754 floating point values with zero before being transferred to clients.
- **Unmodified:** This option allows a driver to transfer IEEE-754 denormalized, normalized, non-number, and infinity values to clients without any conversion or changes.

● **Note:** This property is disabled if the driver does not support floating-point values or if it only supports the option that is displayed. According to the channel's float normalization setting, only real-time driver tags (such as values and arrays) are subject to float normalization. For example, EFM data is not affected by this setting.

● *For more information on the floating-point values, refer to "How To ... Work with Non-Normalized Floating-Point Values" in the server help.*

**Inter-Device Delay:** Specify the amount of time the communications channel waits to send new requests to the next device after data is received from the current device on the same channel. Zero (0) disables the delay.

● **Note:** This property is not available for all drivers, models, and dependent settings.

## Channel Properties – Driver Setup

Property Groups General Serial Communications Write Optimizations Advanced <b>Driver Setup</b>	[-] <b>Driver Setup</b>	
	Station Address	1

**Station Address:** This driver only issues requests when it's polled by the Uni-Telway network controller. The assigned station address determines which poll request the driver responds to in the programmed sequence. Valid range is from 1-253.

### ● Tips:

1. Make sure that the assigned Station Address is valid. Since the driver needs to be polled before it can communicate, verify that the Uni-Telway network controller (i.e. PLC) is polling the driver's range. For example, if the network controller polls devices 1-31, a Station Address of 32 is not valid.
2. Make sure that the 5-layer Device ID is correct. When trying to communicate with one network controller PLC, the Device ID for the PLC should be as follows. Addresses are in hex.
  - Network - 0
  - Station - FE
  - Gate - 0
  - Module - 0
  - Channel - 0
3. Select either Sm\_Frame or Lg\_Frame depending on the Telemecanique PLC model with which communication is being established. For the Telemecanique PLC model TSX17, select the Sm\_Frame option. For all other Telemecanique PLC models, select the Lg\_Frame option.
4. An RS232/485 converter capable of automatic direction control is used. See [Device Setup](#) for converter information.
5. In some Telemecanique PLCs, the **Wait Time** can be configured. The Wait Time is the amount of time the PLC acting as the Uni-Telway network controller waits when it issues poll messages to a device before timing out on the device. The default in most cases is 10 milliseconds. If this time is increased to 20 milliseconds or more, the driver's response time dramatically improves due to the reduced number of missed poll messages. This property is available in the PLC configuration.

## Device Properties – General

A device represents a single target on a communications channel. If the driver supports multiple controllers, users must enter a device ID for each controller.

Property Groups	<input type="checkbox"/> <b>Identification</b>	
General	Name	
	Description	
	Channel Assignment	
	Driver	
	Model	
	ID Format	Decimal
	ID	2

### Identification

**Name:** Specify the name of the device. It is a logical user-defined name that can be up to 256 characters long and may be used on multiple channels.

**Note:** Although descriptive names are generally a good idea, some OPC client applications may have a limited display window when browsing the OPC server's tag space. The device name and channel name become part of the browse tree information as well. Within an OPC client, the combination of channel name and device name would appear as "ChannelName.DeviceName".

**For more information, refer to "How To... Properly Name a Channel, Device, Tag, and Tag Group" in server help.**

**Description:** Specify the user-defined information about this device.

Many of these properties, including Description, have an associated system tag.

**Channel Assignment:** Specify the user-defined name of the channel to which this device currently belongs.

**Driver:** Selected protocol driver for this device.

**Model:** Specify the type of device that is associated with this ID. The contents of the drop-down menu depend on the type of communications driver being used. Models that are not supported by a driver are disabled. If the communications driver supports multiple device models, the model selection can only be changed when there are no client applications connected to the device.

**Note:** If the communication driver supports multiple models, users should try to match the model selection to the physical device. If the device is not represented in the drop-down menu, select a model that conforms closest to the target device. Some drivers support a model selection called "Open," which allows users to communicate without knowing the specific details of the target device. *For more information, refer to the driver documentation.*

**ID:** Specify the device's driver-specific station or node. The type of ID entered depends on the communications driver being used. For many communication drivers, the ID is a numeric value. Drivers that support a Numeric ID provide users with the option to enter a numeric value whose format can be changed to suit the needs of the application or the characteristics of the selected communications driver. The format is set by the driver by default. Options include Decimal, Octal, and Hexadecimal.

### Operating Mode

Property Groups	<input checked="" type="checkbox"/> <b>Identification</b>	
General	<input type="checkbox"/> <b>Operating Mode</b>	
	Data Collection	Enable
	Simulated	No

**Data Collection:** This property controls the device's active state. Although device communications are enabled by default, this property can be used to disable a physical device. Communications are not attempted when a device is disabled. From a client standpoint, the data is marked as invalid and write operations are not accepted. This property can be changed at any time through this property or the device system tags.

**Simulated:** Place the device into or out of Simulation Mode. In this mode, the driver does not attempt to communicate with the physical device, but the server continues to return valid OPC data. Simulated stops physical communications with the device, but allows OPC data to be returned to the OPC client as valid data. While in Simulation Mode, the server treats all device data as reflective: whatever is written to the simulated device is read back and each OPC item is treated individually. The data is not saved if the server removes the item (such as when the server is reinitialized). The default is No.

● **Notes:**

1. Updates are not applied until clients disconnect and reconnect.
  2. The System tag (`_Simulated`) is read only and cannot be written to for runtime protection. The System tag allows this property to be monitored from the client.
  3. In Simulation mode, the item's memory map is based on client update rate(s) (Group Update Rate for OPC clients or Scan Rate for native and DDE interfaces). This means that two clients that reference the same item with different update rates return different data.
  4. When a device is simulated, updates may not appear faster than one (1) second in the client.
- ◆ Simulation Mode is for test and simulation purposes only. It should never be used in a production environment.

## Tag Counts

Property Groups	<input type="checkbox"/> Identification
General	<input type="checkbox"/> Operating Mode
	<input type="checkbox"/> Tag Counts
	Static Tags
	130

**Static Tags:** Provides the total number of defined static tags at this level (device or channel). This information can be helpful in troubleshooting and load balancing.

## Device Properties – Scan Mode

The Scan Mode specifies the subscribed-client requested scan rate for tags that require device communications. Synchronous and asynchronous device reads and writes are processed as soon as possible; unaffected by the Scan Mode properties.

Property Groups	<input type="checkbox"/> Scan Mode
General	Scan Mode
Scan Mode	Respect Client-Specified Scan Rate ▼
	Initial Updates from Cache
	Disable

**Scan Mode:** Specify how tags in the device are scanned for updates sent to subscribing clients. Descriptions of the options are:

- **Respect Client-Specified Scan Rate:** This mode uses the scan rate requested by the client.
- **Request Data No Faster than Scan Rate:** This mode specifies the value set as the maximum scan rate. The valid range is 10 to 99999990 milliseconds. The default is 1000 milliseconds.
  - **Note:** When the server has an active client and items for the device and the scan rate value is increased, the changes take effect immediately. When the scan rate value is decreased, the changes do not take effect until all client applications have been disconnected.
- **Request All Data at Scan Rate:** This mode forces tags to be scanned at the specified rate for subscribed clients. The valid range is 10 to 99999990 milliseconds. The default is 1000 milliseconds.
- **Do Not Scan, Demand Poll Only:** This mode does not periodically poll tags that belong to the device nor perform a read to get an item's initial value once it becomes active. It is the OPC client's responsibility to poll for updates, either by writing to the `_DemandPoll` tag or by issuing explicit device reads for individual items. *For more information, refer to "Device Demand Poll" in server help.*

- **Respect Tag-Specified Scan Rate:** This mode forces static tags to be scanned at the rate specified in their static configuration tag properties. Dynamic tags are scanned at the client-specified scan rate.

**Initial Updates from Cache:** When enabled, this option allows the server to provide the first updates for newly activated tag references from stored (cached) data. Cache updates can only be provided when the new item reference shares the same address, scan rate, data type, client access, and scaling properties. A device read is used for the initial update for the first client reference only. The default is disabled; any time a client activates a tag reference the server attempts to read the initial value from the device.

### Device Properties – Auto-Demotion

The Auto-Demotion properties can temporarily place a device off-scan in the event that a device is not responding. By placing a non-responsive device offline for a specific time period, the driver can continue to optimize its communications with other devices on the same channel. After the time period has been reached, the driver re-attempts to communicate with the non-responsive device. If the device is responsive, the device is placed on-scan; otherwise, it restarts its off-scan time period.

Property Groups	<input checked="" type="checkbox"/> <b>Auto-Demotion</b>	
General	Demote on Failure	Enable
Scan Mode	Timeouts to Demote	3
Timing	Demotion Period (ms)	10000
<b>Auto-Demotion</b>	Discard Requests when Demoted	Disable

**Demote on Failure:** When enabled, the device is automatically taken off-scan until it is responding again.

**Tip:** Determine when a device is off-scan by monitoring its demoted state using the `_AutoDemoted` system tag.

**Timeouts to Demote:** Specify how many successive cycles of request timeouts and retries occur before the device is placed off-scan. The valid range is 1 to 30 successive failures. The default is 3.

**Demotion Period:** Indicate how long the device should be placed off-scan when the timeouts value is reached. During this period, no read requests are sent to the device and all data associated with the read requests are set to bad quality. When this period expires, the driver places the device on-scan and allows for another attempt at communications. The valid range is 100 to 3600000 milliseconds. The default is 10000 milliseconds.

**Discard Requests when Demoted:** Select whether or not write requests should be attempted during the off-scan period. Disable to always send write requests regardless of the demotion period. Enable to discard writes; the server automatically fails any write request received from a client and does not post a message to the Event Log.

### Device Properties – Address

Property Groups	<input checked="" type="checkbox"/> <b>Five Layer Address</b>	
General	Five Layer Network Address	0
Scan Mode	Five-Layer Station Address	FE
Auto-Demotion	Five-Layer Gate Address	0
<b>Address</b>	Five-Layer Module Address	0
Timeout	Five-Layer Channel Address	0

#### Five-Layer Address

This property group specifies the five-layer address information to identify the device connected to the Telemecanique network with the following components:

- Network** 00 - FE (0 - 254)
- Station** 00 - FE (0 - 254)
- Gate** 00 - FE (0 - 254)
- Module** Rack 0 - F (0 - 15) / Module 0 - 7
- Channel** 00 - FE (0 - 254)

## Device Properties – Timeout

Property Groups	[-] <b>Timeout</b>	
General	Response Timeout (ms)	500
Scan Mode	Message Timeout (s)	2
Auto-Demotion	Retries	6
Address		
<b>Timeout</b>		

**Response Timeout:** Specify how long the driver should wait for intermediate responses before timing out. An intermediate response is any single portion of a response frame or poll request from the Uni-Telway network controller. Valid response timeout values range from 20 to 3000 ms. The default is 500 ms.

**Message Timeout:** Specify how long the driver should wait for the Uni-Telway network controller to satisfy a request for data. Valid message timeout values range from 1 to 999 seconds. The default is 2 seconds.

**Retries:** Specify how many times the driver attempt a communications request before considering the request to have failed. The valid range is 1 to 10 retries. The default is 6 retries. The number of retries configured for the application depends largely on the communications environment.

## Device Properties – Redundancy

Property Groups	[-] <b>Redundancy</b>	
General	Secondary Path	Channel.Device 1 ...
Scan Mode	Operating Mode	Switch On Failure
Timing	Monitor Item	
Auto-Demotion	Monitor Interval (s)	300
<b>Redundancy</b>	Return to Primary ASAP	Yes

Redundancy is available with the Media-Level Redundancy Plug-In.

• Consult the website, a sales representative, or the [user manual](#) for more information.

## Data Types Description

---

Data Type	Description
Boolean	Single bit
Word	Unsigned 16-bit value bit 0 is the low bit bit 15 is the high bit
Short	Signed 16-bit value bit 0 is the low bit bit 14 is the high bit bit 15 is the sign bit
DWord	Unsigned 32-bit value bit 0 is the least significant bit bit 31 the most significant bit
Long	Signed 32-bit value bit 0 is the least significant bit bit 30 the most significant bit bit 31 is the sign bit

## Address Descriptions

Select a model type below to see address information for PLCs of that type. Telemecanique Devices that do not support the full 128-byte data field provided by the Telemecanique Uni-Telway protocol are considered Small Frame. One example of a Small Frame device is the TSX17-20.

[Small Frame](#)

[Large Frame](#)

## Small Frame Addresses

The default data types for dynamically defined tags are shown in **bold**.

Device Type	Range	Data Type	Access
Internal Word Memory	MW00000-MW32767* MWxxxx.00 - MWxxxx.15 MWxxxx.L L = Number of words used for String Range: 1-15	Short, <b>Word</b> , Long, DWord Boolean String	Read / Write Read Only Read / Write
Internal Bit Memory	M0000-M4095	Boolean	Read / Write
Constant Memory	KW00000-KW32767* KWxxxx.00-KWxxxx.15	Short, <b>Word</b> , Long, DWord Boolean	Read Only Read Only
Timer Preset	T000.P-T127.P	Short, <b>Word</b>	Read / Write
Timer Value	T000.V-T127.V	Short, <b>Word</b>	Read Only
Timer Done Bit	T000.Q-T127.Q	Boolean	Read Only
Counter Preset	C000.P-C255.P	Short, <b>Word</b>	Read / Write
Counter Value	C000.V-C255.V	Short, <b>Word</b>	Read Only
Counter Done Bit	C000.D-C255.D	Boolean	Read Only
PL7 Timer Preset	TP000.P-TP127.P	Short, <b>Word</b>	Read / Write
PL7 Timer Value	TP000.V-TP127.V	Short, <b>Word</b>	Read Only
PL7 Timer Done Bit	TP000.Q-TP127.Q	Boolean	Read Only
IEC Timer Preset	TM000.P-TM127.P	Short, <b>Word</b>	Read / Write
IEC Timer Value	TM000.V-TM127.V	Short, <b>Word</b>	Read Only
IEC Timer Done Bit	TM000.Q-TM127.Q	Boolean	Read Only
PL7 Counter Preset	CP000.P-CP255.P	Short, <b>Word</b>	Read / Write
PL7 Counter Value	CP000.V-CP255.V	Short, <b>Word</b>	Read Only
PL7 Counter Done Bit	CP000.D-CP255.D	Boolean	Read Only

\*Supports array notation. To specify an array, append the array size to the address specification as follows: address[array size] or address[rows][cols]. Small Frame arrays can have a maximum size of 15 word elements.

### Notes:

1. Use PL7/IEC Timers (TP, TM Device Types) and PL7 Counter (CP Device Type) with TSX Micro or Premium PLCs. These types are not supported when using TSX Nano PLC.
2. Maximum value for TP, TM and CP Device Types Preset is 9999. A write of a value greater than Maximum will fail with an error '06' (invalid write value).
3. Timer and Counter types 'T' and 'C' are not supported when using TSX Nano, Micro or Premium PLCs and will fail with a "Negative Response Returned" error message.

## Large Frame Addresses

The default data types for dynamically defined tags are shown in **bold**.

Device Type	Range	Data Type	Access
Internal Word Memory	MW00000-MW32767* MWxxxx.00 - MWxxxx.15 MWxxxx.L L = Number of words used for String Range: 1-60	Short, <b>Word</b> , Long, DWord Boolean String	Read / Write Read Only Read / Write
Internal Bit Memory	M0000-M4095	Boolean	Read / Write
Constant Memory	KW00000-KW32767* KWxxxx.00-KWxxxx.15	Short, <b>Word</b> , Long, DWord Boolean	Read Only Read Only
Timer Preset	T000.P-T127.P	Short, <b>Word</b>	Read / Write
Timer Value	T000.V-T127.V	Short, <b>Word</b>	Read Only
Timer Done Bit	T000.Q-T127.Q	Boolean	Read Only
Counter Preset	C000.P-C255.P	Short, <b>Word</b>	Read / Write
Counter Value	C000.V-C255.V	Short, <b>Word</b>	Read Only
Counter Done Bit	C000.D-C255.D	Boolean	Read Only
PL7 Timer Preset	TP000.P-TP127.P	Short, <b>Word</b>	Read / Write
PL7 Timer Value	TP000.V-TP127.V	Short, <b>Word</b>	Read Only
PL7 Timer Done Bit	TP000.Q-TP127.Q	Boolean	Read Only
IEC Timer Preset	TM000.P-TM127.P	Short, <b>Word</b>	Read / Write
IEC Timer Value	TM000.V-TM127.V	Short, <b>Word</b>	Read Only
IEC Timer Done Bit	TM000.Q-TM127.Q	Boolean	Read Only
PL7 Counter Preset	CP000.P-CP255.P	Short, <b>Word</b>	Read / Write
PL7 Counter Value	CP000.V-CP255.V	Short, <b>Word</b>	Read Only
PL7 Counter Done Bit	CP000.D-CP255.D	Boolean	Read Only

\*Supports array notation. To specify an array, append the array size to the address specification as follows: address [array size] or address[rows][cols]. Large Frame arrays can have a maximum size of 60 word elements.

### Notes:

1. Use PL7/IEC Timers (TP, TM Device Types) and PL7 Counter (CP Device Type) with TSX Micro or Premium PLCs. These types are not supported when using TSX Nano PLC.
2. Maximum value for TP, TM and CP Device Types Preset is 9999. A write of a value greater than Maximum will fail with an error '06' (invalid write value).
3. Timer and Counter types 'T' and 'C' are not supported when using TSX Nano, Micro or Premium PLCs and will fail with a "Negative Response Returned" error message.

## Error Descriptions

---

The following error / warning messages may be generated. Click on the link for a description of the message.

### Address Validation

#### [Missing address](#)

[Device address <address> contains a syntax error](#)

[Address <address> is out of range for the specified device or register](#)

[Data type <type> is not valid for device address <address>](#)

[Device address <address> is read only](#)

### Serial Communications

[COMn does not exist](#)

[Error opening COMn](#)

[COMn is in use by another application](#)

[Unable to set comm properties on COMn](#)

[Communications error on <channel name> \[<error mask>\]](#)

### Device Status Messages

[Device <device name> is not responding](#)

[Unable to write to <address> on device <device name>](#)

[Device <device name> responded with error <error byte> \(Tag <address>, Size <size>\)](#)

[Device <device name> negative response returned \(Tag <address>, Size <size>\)](#)

[Device <device name> response invalid \(Tag <address>, Size <size>\)](#)

## Missing address

---

### Error Type:

Warning

### Possible Cause:

A tag address that has been specified dynamically has no length.

### Solution:

Re-enter the address in the client application.

## Device address <address> contains a syntax error

---

### Error Type:

Warning

### Possible Cause:

A tag address that has been specified dynamically contains one or more invalid characters.

### Solution:

Re-enter the address in the client application.

## Address <address> is out of range for the specified device or register

---

### Error Type:

Warning

### Possible Cause:

A tag address that has been specified dynamically references a location that is beyond the range of supported locations for the device.

### Solution:

Verify the address is correct; if it is not, re-enter it in the client application.

---

**Data type <type> is not valid for device address <address>**

---

**Error Type:**

Warning

**Possible Cause:**

A tag address that has been specified dynamically has been assigned an invalid data type.

**Solution:**

Modify the requested data type in the client application.

---

**Device address <address> is read only**

---

**Error Type:**

Warning

**Possible Cause:**

A tag address that has been specified dynamically has a requested access mode that is not compatible with what the device supports for that address.

**Solution:**

Change the access mode in the client application.

---

**COMn does not exist**

---

**Error Type:**

Fatal

**Possible Cause:**

The specified COM port is not present on the target computer.

**Solution:**

Verify that the proper COM port has been selected.

---

**Error opening COMn**

---

**Error Type:**

Fatal

**Possible Cause:**

The specified COM port could not be opened due to an internal hardware or software problem on the target computer.

**Solution:**

Verify that the COM port is functional and may be accessed by other Windows applications.

---

**COMn is in use by another application**

---

**Error Type:**

Fatal

**Possible Cause:**

The serial port assigned to a device is being used by another application.

**Solution:**

Verify that the correct port has been assigned to the channel.

---

## Unable to set comm properties on COMn

---

**Error Type:**

Fatal

**Possible Cause:**

The serial properties for the specified COM port are not valid.

**Solution:**

Verify the serial properties and make any necessary changes.

---

## Communications error on <channel name> [<error mask>]

---

**Error Type:**

Serious

**Error Mask Definitions:**

**B** = Hardware break detected.

**F** = Framing error.

**E** = I/O error.

**O** = Character buffer overrun.

**R** = RX buffer overrun.

**P** = Received byte parity error.

**T** = TX buffer full.

**Possible Cause:**

1. The serial connection between the device and the host PC is bad.
2. The communications properties for the serial connection are incorrect.

**Solution:**

1. Verify the cabling between the PC and the PLC device.
2. Verify that the specified communications properties match those of the device.

---

## Device <device name> is not responding

---

**Error Type:**

Serious

**Possible Cause:**

1. The serial connection between the device and the host PC is broken.
2. The communications properties for the serial connection are incorrect.
3. The named device may have been assigned an incorrect Network ID.
4. The response from the device took longer to receive than the amount of time specified in the "Request Timeout" device property.

**Solution:**

1. Verify the cabling between the PC and the PLC device.
2. Verify that the specified communications properties match those of the device.
3. Verify that the Network ID given to the named device matches that of the actual device.
4. Increase the Request Timeout property so that the entire response can be handled.

## Unable to write to <address> on device <device name>

---

### Error Type:

Serious

### Possible Cause:

1. The serial connection between the device and the host PC is broken.
2. The communications properties for the serial connection are incorrect.
3. The named device may have been assigned an incorrect Network ID.

### Solution:

1. Verify the cabling between the PC and the PLC device.
2. Verify that the specified communications properties match those of the device.
3. Verify that the Network ID given to the named device matches that of the actual device.

## Device <device name> responded with error <error byte> (Tag <address>, Size <size>)

---

### Error Type:

Warning

### Possible Cause:

See the Solution.

### Solution:

Use following tables to decode the error byte.

#### Read Error Byte Possible Values

Error Byte	Description
00h	Read performed
02h	Instance number outside configuration limits
03h	Number of bits to read not a multiple of 8
04h	Object not configured in PL7 application
05h	Response buffer overflow
07h	Access property, object label or element number incorrect
08h	Access temporarily not possible
09h	Number of reads requested equal to zero

#### Write Error Byte Possible Values

Error Byte	Description
00h	Write operation performed
01h	Element write-protected
02h	Instance number outside configuration limits
04h	Object not configured in PL7 application
06h	Invalid write value
08h	Access temporarily not possible
09h	Number of write operations requested equal to zero

**Device <device name> Negative response returned (Tag <address>, Size <size>)**

---

**Error Type:**

Serious

**Possible Cause:**

An unsupported type was used.

**Solution:**

Use a supported type.

**Device <device name> response invalid (Tag <address>, Size <size>)**

---

**Error Type:**

Warning

**Possible Cause:**

Either an unsupported type was used or the PLC does not support the type.

**Solution:**

Use a supported type.

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